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PATENT
1379-1-014

IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

APPLICANTS	:	Teodor AKINFIEVA *et al*
APPLICATION NO.	:	PCT/ES00/00484
U.S. SERIAL NO.	:	NOT YET ASSIGNED
FILED	:	HEREWITH
FOR	:	DEVICE OF A WORKING ELEMENT WITH TWO DEGREES OF MOBILITY

ASSISTANT COMMISSIONER FOR PATENTS
BOX PCT
WASHINGTON, D.C. 20231

Sir:

Prior to calculating the fees pursuant to the entry into the National Phase of the above-identified Application, please amend the claims as follows:

IN THE CLAIMS:

Please amend Claims 4, 6, 7, 8, 9 and 10 as follows:

4. (Amended) Guidance of a working element with two degrees of mobility, according to claim 2, wherein the connection between the working element and the two movable links is implemented with aid of an articulation.

6.(Amended) Guidance of a working element with two degrees of mobility, according to claim 2, wherein lengths of the movable links are equal.

7.(Amended) Guidance of a working element with two degrees of mobility, according to claim 2, wherein the connection between the base and an extreme of the movable links is achieved in such a manner that it permits a movement in coincident trajectories over parallel lines.

8. (Amended) Guidance of a working element with two degrees of mobility, according to claim 2, wherein the connection between the base and an extreme of the movable links is achieved in such a manner that it permits movement of these extremes along trajectories which are situated over a same straight line.

9. (Amended) Guidance of a working element with two degrees of mobility, according to claim 2, wherein the kinematic connection between at least one of the motors and its corresponding movable link is self-blocking.

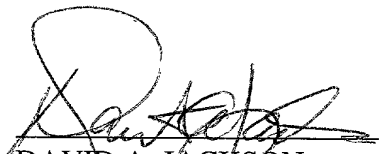
10. (Amended) Guidance of a working element with two degrees of mobility, according to claim 2, wherein by using different working elements in a same base, for at least two of them, the lengths of the movable links corresponding to one of the working elements are larger than the lengths of the movable links corresponding to another working element.

REMARKS

The above amendments are submitted herewith to reduce multiple dependencies and to conform the claims more closely to U.S. practice.

Entry of the foregoing amendments and early and favorable processing in the National Phase before the United States Patent and Trademark Office is courteously solicited.

Respectfully submitted,



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VERSION WITH MARKINGS TO SHOW CHANGES MADE

In The Claims:

Claims 4, 6, 7, 8, 9 and 10 have been amended as follows:

4. (Amended) Guidance of a working element with two degrees of mobility, according to claim[s] 2 [and 3], wherein the connection between the working element and the two movable links is implemented with aid of an articulation.

6.(Amended) Guidance of a working element with two degrees of mobility, according to [any of claims 2 to 5] claim 2, wherein lengths of the movable links are equal.

7.(Amended) Guidance of a working element with two degrees of mobility, according to [any of claims 2 to 5] claim 2, wherein the connection between the base and an extreme of the movable links is achieved in such a manner that it permits a movement in coincident trajectories over parallel lines.

8. (Amended) Guidance of a working element with two degrees of mobility, according to [any of claims 2 to 6] claim 2, wherein the connection between the base and an extreme of the movable links is achieved in such a manner that it permits movement of these extremes along trajectories which are situated over a same straight line.

9. (Amended) Guidance of a working element with two degrees of mobility, according to [any of claims 2 to 8] claim 2, wherein the kinematic connection between at least one of the motors and its corresponding movable link is self-blocking.

10. (Amended) Guidance of a working element with two degrees of mobility, according to [any of claims 2 to 9] claim 2, wherein by using different working elements in a same base, for at least two of them, the lengths of the movable links corresponding to one of the working elements are larger than the lengths of the movable links corresponding to another working element.